**PMA12** SELF-SUPPORTING LINEAR POSITION TRANSDUCER WITH MAGNETIC PULLING



#### **Principal characteristics**

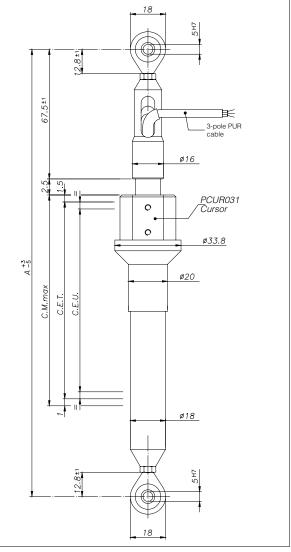
- The PMA-12 transducer, a development of the PME series, is designed for installation with self-aligning joints.
- The IP67 protection level makes the PMA-12 highly suitable for humid and wet environments and in temporary immersion (CEI EN 60529).
- · Available only with cable output.
- Ideal for applications on metalworking and ceramics machines, as well as on earth-moving machines and utility vehicles. Recommended in all cases where the angle of the drive axle changes constantly.

#### **TECHNICAL DATA**

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Useful electical stroke (C.E.U.)	50 to 1000mm
Independent linearity	see table
(within C.E.U.)	
Resolution	Infinite
Repeatability	≤ 0,08 mm
Hysteresis	≤ 0,25mm
Electrical connection	PMA12 F 3-pole shielded cable 1m
Protection level	IP67 (CEI EN 60529)
Life	> 25x10 <sup>6</sup> m strokes, or
	> 100x10 <sup>6</sup> operations, whichever
	is less
Displacement speed	≤ 5 m/s
Max. acceleration	≤ 10m/s <sup>2</sup> displacement
Shock test DIN IEC68T2-27	50g, 11ms single stroke
Vibraziotions DIN IEC68T2-6	12g, 102000Hz
Cursor dragging force	≤ 0.5 N
Displacement sensitivity	da 0.05 a 0.1 mm
(no hysteresis)	
Tracking error	See table
Tolerance on resistance	±20%
Recommended cursor	< 0,1 µA
current	
Maximum cursor current in	
case of bad performances	10mA
Maximum applicable voltage	See table
Electrical isolation	>100MΩ at 500V=, 1bar, 2s
Dielectric strength	< 100µA at 500V~, 50Hz, 2s, 1bar
Dissipation at 40°C	See table
(0W at 120°C)	
Thermal coefficient	-200 +200 ppm/°C typical
of resistance	
Actual Temperature Coefficient	≤ 5 ppm/°C typical
of the output voltage	
Working temperature	-30+100°C
Storage temperature	-50+120°C
Material for transducer	Anodised aluminium, PSU
case	
Material for cursor magnets	POM
Mounting	Self-aligning joints with adjustable
-	distance between centres

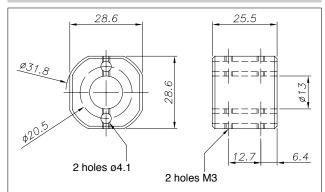
### **MECHANICAL DIMENSIONS**



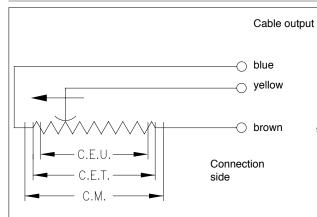
Important: all data shown in the catalog for linearity values and temperature coefficients are valid when the sensor is used as voltage divider with maximum current of Ic+0.1µA in the circuit.

ELECTRICAL / MECHANICAL DATA																							
MODEL		50	100	150	200	250	300	350	400	450	500	550	600	650	700	750	800	850	900	950	1000		
Useful electrical stroke (U.E.S.) + 1 / -0	mm		Model																				
Theoretical electrical stroke (T.E.S.) ± 1	mm		U.E.S. + 1																				
Resistance (on T.E.S.)	kΩ	5							10						20								
Independent linearity (within U.E.S.)	±%	0,1							0,05														
Dissipation at 40°C (0W at 120°C)	w	1	2	3																			
Max. applicable voltage	v	40	40 60																				
Mechanical stroke MC	mm		U.E.S. + 3,5																				
Case length (A)	mm		U.E.S. + 155																				

## **CURSOR PCUR031**



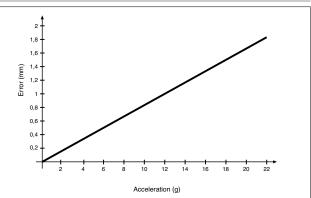
# **ELECTRICAL CONNECTIONS**



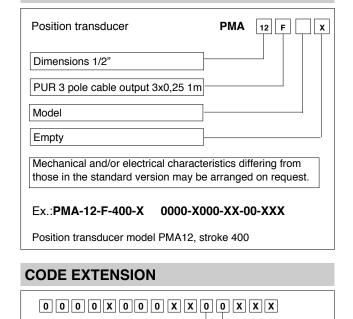
### INSTALLATION INSTRUCTIONS

- Respect the indicated electrical connections (DO NOT use the transducer as a variable resistance)
- When calibrating the transducer, be careful to set the stroke so that the output does not drop below 1% or rise beyond 99% of the supply voltage.

# TRACKING ERROR



## **ORDER CODE**



 CABLE LENGTH (version F standard 1mt)

 Output F
 00 =1mt
 02 =2mt
 03 =3mt
 04 =4mt
 05 =5mt

 10 =10mt
 15 =15mt

GEFRAN spa reserved the right to make aesthetic or functional changes at any time and without notice.



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